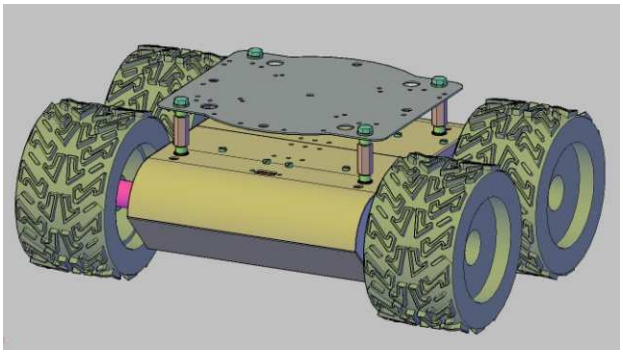


- *4 roues motrices*
- *Architecture modulaire et ouverte*
- *Contrôlable en RS232 ou en Wifi*
- *PC x86 embarqué avec une image Xpe ou Linux Ubuntu*

Wifibot *Lab V3*

Robot WIFIBOT Lab V3

Le Wifibot Lab est une plate forme robotique **modulaire**, qui permet de couvrir un large spectre lié à la **robotique mobile**, à **l'informatique industrielle** et **aux réseaux sans fil**. Utilisée par un nombre croissant de centre R&D, d'école, d'université, et de laboratoire dans le monde, elle se distingue par sa simplicité et son efficacité.

Le système de base est composé d'un **châssis en aluminium** anodisé, d'une **camera USB motorisée**, de **4 capteurs infra rouge** et d'une nappe laser **Hokuyo URG-04LX-UG01 ou UTM-30LX en option**. Le châssis du robot est contrôlable en utilisant un port RS232. L'unité de calcule embarquée qui envoie les commandes au robot est une carte industrielle Intel Atom D510 double coeur au format 3.5 pouces avec une image du système d'exploitation XP embedded SP3 ou Linux Ubuntu, utilisés dans le monde de l'embarqué. Une carte WIFI assure la liaison sans fils au système avec le point **d'accès configuré fourni gratuitement**.

Les utilisateurs peuvent ainsi modifier ou concevoir des programmes directement sur le robot (VGA ou bureau distant via WIFI).

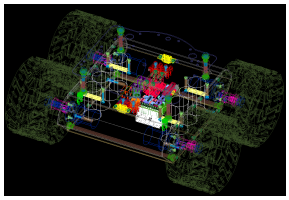
Diverses interfaces de contrôle et API sont proposées aux utilisateurs avec le code source en C/C++. Des logiciels comme **ROS, RTMAPS, URBI, Matlab** ou d'autres peuvent s'interfacer facilement du fait de la simplicité du protocole **ouvert** RS232 ou Ethernet.

La carte bas niveau moteur est aussi ouverte et programmable en C avec le débuggeur ICD2/3 et l'outil MPLAB de Microchip, ou simplement, en utilisant le bootloader intégré.

Divers options peuvent être ajouté au cour du temps: PC embarqué plus puissant (coreI5/I7), GPS, Kinect, Carte d'acquisition multi camera H264, carte firewire, Camera avec DSP Texas Davincy etc … et cela selon les orientations des enseignements ou de vos recherches. etc...

Option

www.wifibot.com



Windows Embedded

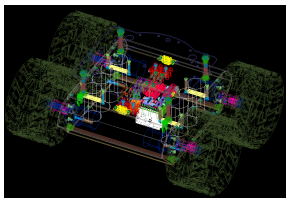
Wifibot *Lab V3*

Spécifications par défaut

Capteurs moteur:	2 codeurs en quadrature effet hall 2048 tics par tour de roue montés à l'avant.
Control vitesse :	2 x PID sur 1 x DSPIC Microchip 33f programmés en C Bootloader Débuggeur ICD2/3 (option)
Moteurs:	4x moteurs 12V Réduction 52:1 planétaire 156 rpm
Dimensions:	L : 30 cm W : 35 cm H : 15 cm W : 3.5Kg
Alimentation Batteries:	12.8V 10AH LIFEPO4 Alimentation DC18V Path Power Managment **Chargeur LIFEPO4 dans le robot** (on peut utiliser le robot pendant sa charge)
Bus de contrôle interne:	**RS232.** Le protocole est très simple et permet de contrôler le robot via l'API en C/C++ ou par n'importe qu'elle logiciel du commerce comme ROS, MatLab, RTMAPS, Robotics Studio, URBI …
Protocole de contrôle distant :	Socket TCP/UDP via WIFI ou RJ45
Calculateur:	Carte industrielle Intel Atom D510 double coeur 1.6Ghz 1G Ram / 4G CF 4 x USB 2.0 4 x RS232/485 1 x Mini-Pci + 1x mini pcie …
Capteurs:	4 capteurs infra rouge 1 web cam Pan et Tilt 1 Lidar Hokuyo 4m ou 30m **en option**
Logiciels:	API C++ de contrôle du robot interfaces de contrôle distante Serveur web embarqué vidéo

WIFI AP (included)

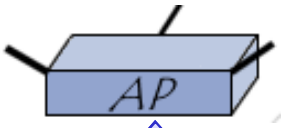
DC 18V POWER (included)



Architecture haut niveau

Wifibot ***Lab V3***

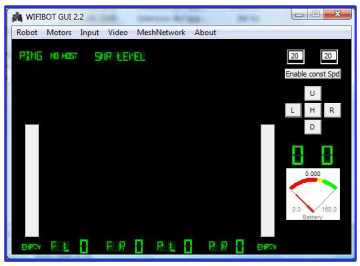
WIFI
a/b/g



Ethernet

Mini-PCI

Calculteur PC



IHM distante

PC Distant

USB

USB

RS232

Serveur Web
MJPEG

ICD3 (option)
or bootloader

2 x IO

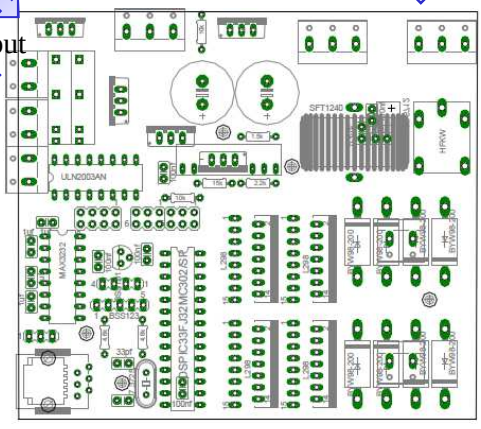
Relay

Power output

Camera

Option

4m Lidar



Carte Moteur DSPIC 33F

Robot

Châssis Wifibot Lab

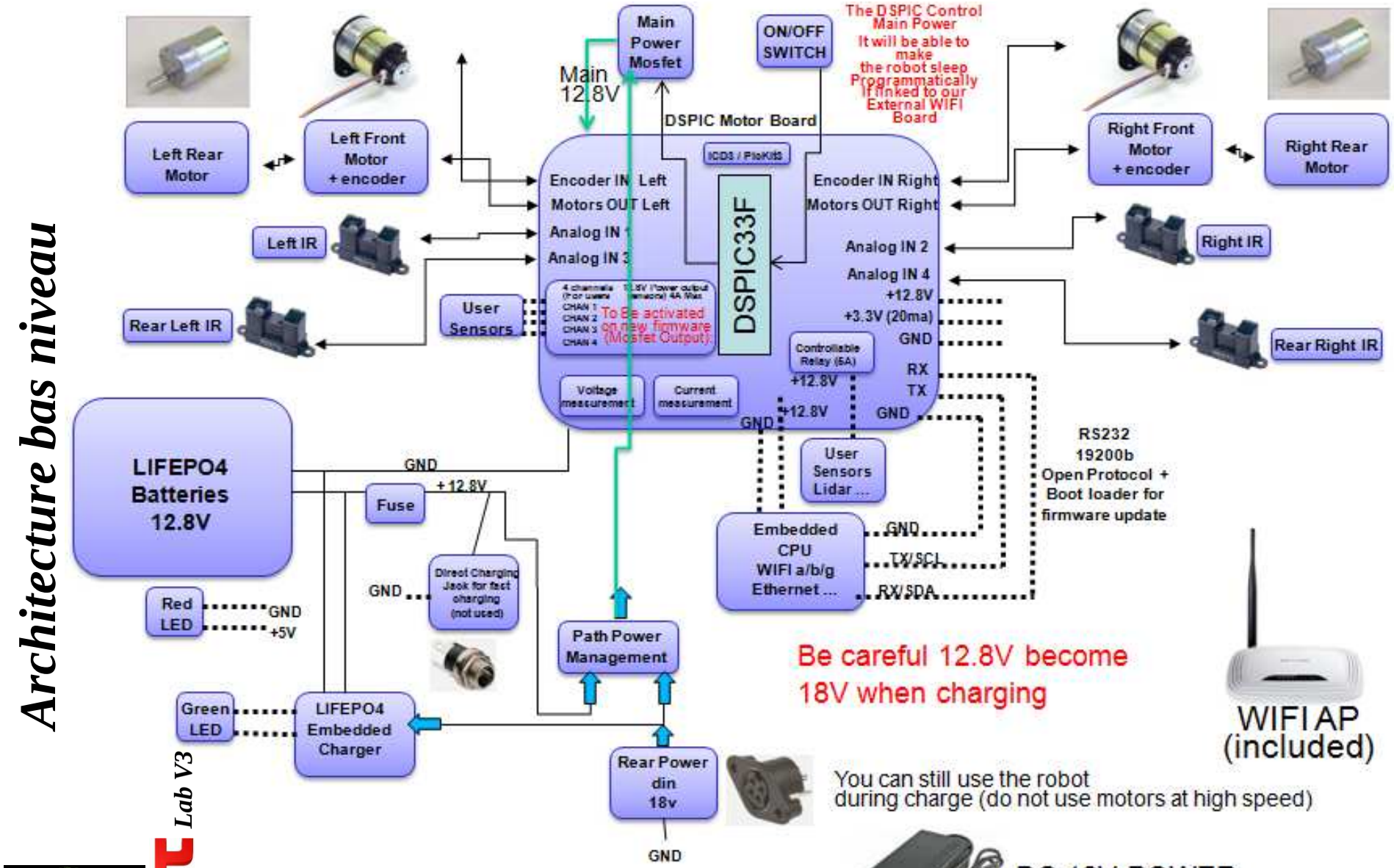
Analog

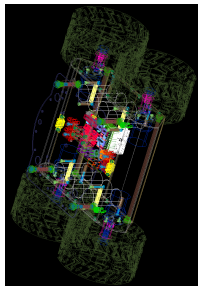
PWM

4 x Capteurs IR

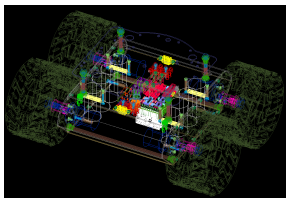
Moteur + Codeur Hall

Architecture bas niveau





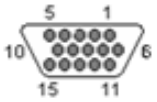
WifiBOT *Lab V3*



Architecture bas niveau (DSUB15 utilisateur)

Lab V3

DSUBF



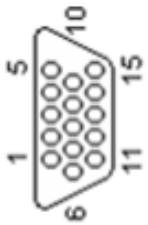
HD-D-sub-15 Female

Be careful 12.8V become 18V when charging so check that your device is18V tolerant or use a DC/DC

DsubF-1 et 2 -> +12.8V (8A Max, embedded PC, other device)
DsubF-6 à 10 -> GND
DsubF-3 -> Relay 1 +12.8V (5A Max)
DsubF-4 et 5 -> Relay2 (not used)
DsubF-15 -> 12.8V (Linked to the Main Switch, 300mA)

To Be activated on new firmware (Mosfet Power Output):
DsubF-11 -> Channel 1 : 12.8V (4A)
DsubF-12 -> Channel 2 : 12.8V (4A)
DsubF-13 ->Channel 3 : 12.8V (4A)
DsubF-14 -> Channel 4 : 12.8V (4A)

DSUBM

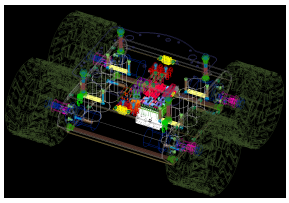


HD-D-sub 15 Male

Serial port for Embedded PC:
DSUB15M-6 -> DSUB9F-3
DSUB15M-7 -> DSUB9F-2
DSUB15M-9 -> DSUB9F-5

Infrared Sensors:
DSUB15M-3 -> Infra1-data
DSUB15M-8 -> Infra1-gnd
DSUB15M-1 -> Infra1-+5V
DSUB15M-4 -> Infra2-data
DSUB15M-8 -> Infra2-gnd
DSUB15M-1 -> Infra2-+5V
DSUB15M-5 -> Infra3-data
DSUB15M-14 -> Infra3-gnd
DSUB15M-2 -> Infra3-+5v
DSUB15M-10 -> Infra4-data
DSUB15M-14 -> Infra4-gnd
DSUB15M-2 -> Infra4-+5V

FUTURE USE:
DsubM-11 -> free dspic IO (future use)
DsubM-12 -> free dspic IO (future use)
DsubM-13 -> not used
DsubM-14 -> GND
DsubM-15 -> 3.3V (20mA)



Annexe 1

Lab V3

LE-376

3.5" embedded board with Intel® Atom™ dual-core Solution

LE-376 consists of the 13W Intel ATOM D510 and ICH8M, Graphic Processing Unit features power-efficient 32-bit 3D graphics core based on Intel GMA 3150 architecture, video capability with up to 384MB of shared graphics memory, delivers sophisticated graphics for large display applications and with Dual display types such as VGA+LVDS, Enables smoother playback for MPEG-2 codec, a standard video compression format used on Blu-ray, DVDs, broadcasting, and broadband content.

Specification

Form Factor	3.5" embedded board
CPU	Intel® Atom™ D510, 1.66GHz, 1MB cache (LE-376A) Package type : Micro-FCBGA (FCBGA559)
Memory	1 x 200-pin DDR2-667 SO-DIMM up to 4GB (LE-376H/A) Support Non-ECC, unbuffered memory only
Chipset	Intel® ICH8M
Real Time Clock	Chipset integrated RTC with onboard lithium battery
Watchdog Timer	Generates a system reset internal timer for 1min/sec ~ 255min/sec
Power Management	ACPI 2.0 compliant, supports power saving mode
Integrated Graphics	Intel® integrated extreme GMA 3150 Technology
Video Memory	Up to 384MB shared with system memory
LVDS Interface	Chipset Integrated 18-bit single channel LVDS
Serial ATA Interface	2 x SATAII interface with 300MB/s transfer rate
Solid State Disk	1 x Compact Flash Type-II
Audio Interface	Intel® ICH8M integrated with Realtek ALC888 HD Codec
LAN Interface	3 x Intel® 82583V Gigabit Ethernet controller
Expansion Interface	1 x PCIe mini card & 1 x Mini-PCI socket
Internal I/O Port	1 x Audio, 4 x USB2.0, 1 x LVDS, 1 x LCD Inverter, 1 x LPT 1 x RS232/4224/5, 4 x RS232, 1 x SMBUS, 1 x IrDA
External I/O Port	1 x USB, 3 x RJ45 LAN, 1 x DB15 VGA, 1 x RS232
Power Requirement	DC 9V ~ 24V input

Annexe 2

WLAN 802.11a/b/g mini-PCI Module

DCMA-81

SPECIFICATION

Frequency Band	➢ 2.312 – 2.472GHz, 2.484 GHz ➢ U-NII: 5.15 - 5.35GHz, 5.725 - 5.825GHz ➢ ISM: 5.725 – 5.850 GHz ➢ DSRC: 5.850 – 5.925 GHz ➢ Europe: 5.15 - 5.35GHz, 5.47 - 5.725GhHz ➢ Japan: 4.90 – 5.00GHz, 5.03 – 5.091GHz, 5.15 – 5.35GHz
Modulation technique	➢ **802.11 a/b/g** DSSS (DBPSK, DQPSK, CCK) OFDM (BPSK,QPSK, 16-QAM, 64-QAM)
Host interface	Half size Mini PCI Type 3A
Channels support	➢ **802.11b/g** US/Canada: 11 (1 ~ 11) Major European country: 13 (1 ~ 13) France: 4 (10 ~ 13) Japan: 11b: 14 (1~13 or 14th), 11g: 13 (1 ~ 13) ➢ **802.11a** US/Canada:12 non-overlapping channels Europe: 19 non-overlapping channel Japan: 4 non-overlapping channels
Output power	➢ A Mode: +17dBm at 6, 9, 12, 18, and 24Mbps +16dBm at 36Mbps +14dBm at 48Mbps +13dBm at 54Mbps ➢ B Mode: +19dBm at 1,2, 5.5, and 11Mbps ➢ G Mode: +17dBm at 6, 9, 12, 18, 24 and 36Mbps +16dBm at 48Mbps +15dBm at 54Mbps
Operation distance	➢ **802.11a:** Outdoor: 85m@54Mbps, 250m@6Mbps Indoor: 20m@54Mbps, 40m@6Mbps ➢ **802.11b:** Outdoor: 250m@11Mbps, 300m@1Mbps Indoor: 30m@11Mbps, 50m@1Mbps ➢ **802.11g**: Outdoor: 80m@54Mbps, 250m@6Mbps Indoor: 15m@54Mbps, 35m@6Mbps
Operation System supported	➢ Windows® 2K, XP
Dimension	➢ 59.75mm(L) * 25.50mm (W) * 5mm (H)
Security	➢ 64-bit,128-bit, 152-bit WEP Encryption ➢ 802.1x Authentication ➢ AES-CCM & TKIP Encryption
Operation mode	➢ Infrastructure & Ad-hoc mode
Operation temperature	➢ 0°C ~ 70°C
Storage temperature	➢ -20°C ~ 70°C

Annexe 3

108M Wireless Access Point
TL-WA601G

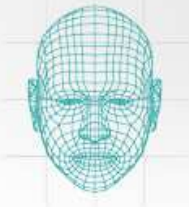
Specifications:

Standards	IEEE 802.11g, IEEE 802.11b
Interface	1 10/100M auto-sensing LAN Port
Wireless Signal Rates With Automatic Fallback	Super G™ : 108M 11g: 54/48/36/24/18/12/9/6M(dynamic) 11b: 11/5.5/2/1M(dynamic)
Frequency Range	2.4-2.4835GHz
Wireless Transmit Power	20dBm(Max)
Antenna	3dBi detachable Omni directional antenna
Modulation Technology	IEEE 802.11b: DQPSK, DBPSK, DSSS, and CCK IEEE 802.11g: BPSK, QPSK, 16QAM, 64QAM, OFDM
Receiver Sensitivity	108M: -68dBm@10% PER 54M: -68dBm@10% PER 11M: -85dBm@8% PER 6M: -88dBm@10% PER 1M: -90dBm@8% PER 256K: -105dBm@8% PER
Power Supply Unit	Input: localized to country of sale Output: 9VAC / 0.8A linear PSU
Operating temperature	0°C~40°C (32°F~104°F)
Storage temperature	-40°C~70°C (-40°F~158°F)
Relative humidity	10% ~ 90%, non condensation
Storage Humidity	5%~95% non-condensing
Dimensions	6.2×4.3×1.3 in. 158×110×32 mm

Annexe 4

Technical Specifications

- Motorized tracking (189° horizontal and 102° vertical)
- Carl Zeiss® optics
- Autofocus lens system
- Ultra-high resolution 2-megapixel sensor with RightLight™ 2 Technology
- Color depth: 24-bit true color
- Video capture: Up to 1600 by 1200 pixels (HD quality)
- Still-image capture: 8 megapixels (with software enhancement)
- Built-in microphone with RightSound™ Technology
- Frame rate: Up to 30 frames per second
- High-Speed USB 2.0
- Logitech QuickCam® software (with Video Effects™, filters, avatars, and face accessories)
- Works with Skype™, Windows Live™ Messenger, Yahoo®, AOL® and other compatible instant messaging applications



Motorized tracking

It keeps you right in the middle of the picture, offering 189-degree field of view and 102-degree tilt.

Carl Zeiss® optics

You'll enjoy razor-sharp images from a lens designed with the help of one of the pioneers in the industry. Find out more about why our collaboration with Carl Zeiss benefits you.

Learn more.

Advanced autofocus

Your images stay razor sharp, even in close-ups (up to 10 cm from the camera lens) with built-in autofocus. Learn all about Logitech autofocus.

Learn more.

HD video recording

Your friends and family can see you in widescreen video at HD quality (720p).

Higher-megapixel performance

With its true 2-megapixel sensor, with up to 8-megapixel photos (software enhanced), every video call and photo will look sharp. Megapixels? Sensor? Why is image quality so important?

Learn more.

RightLight™ 2 technology

Even if you make a video call in dim or poorly backlit settings, the camera will intelligently adjust to produce the best possible image. Find out what's right about RightLight 2 technology.

Learn more.

GP2Y0A02YK

Long Distance Measuring Sensor

■ Features

1. Less influence on the colors of reflected objects and their reflectivity, due to optical triangle measuring method
2. Distance output type
   (Detection range:20 to 150cm)
3. An external control circuit is not necessary
   Output can be connected directly to a microcomputer

■ Applications

1. For detection of human body and various types of objects in home appliances, OA equipment, etc

■ Absolute Maximum Ratings

(T_a=25°C)

Parameter	Symbol	Rating	Unit
Supply voltage	V_{CC}	−0.3 to +7	V
*1 Output terminal voltage	V_O	−0.3 to V_{CC} +0.3	V
Operating temperature	T_{opr}	−10 to +60	°C
Storage temperature	T_{stg}	−40 to +70	°C

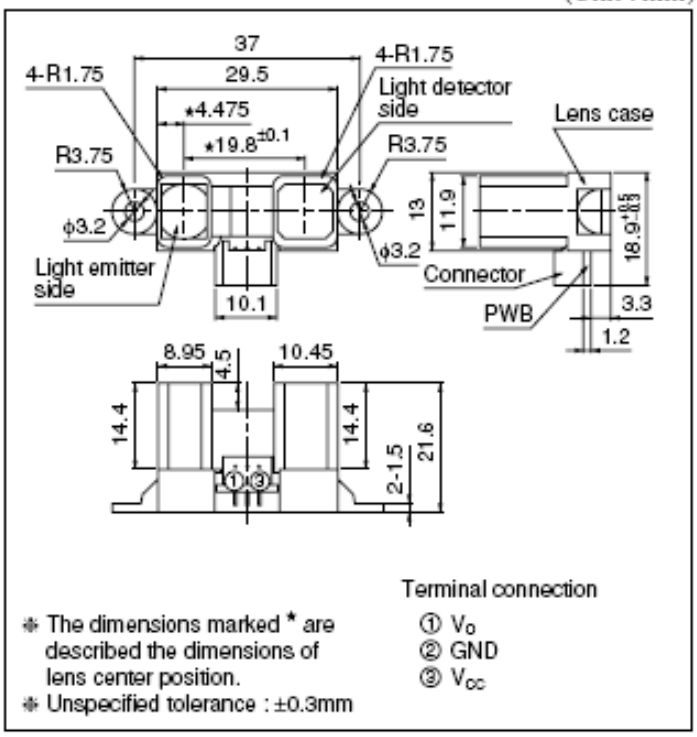
*1 Open collector output

■ Recommended Operating Conditions

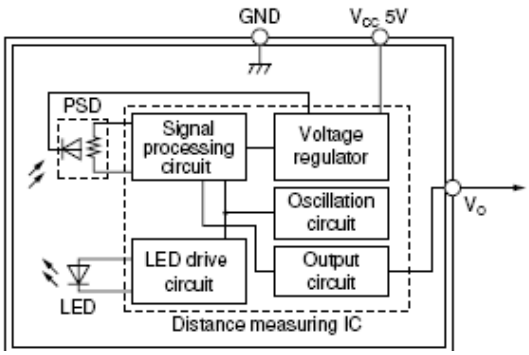
Parameter	Symbol	Rating	Unit
Operating Supply voltage	V_{CC}	4.5 to 5.5	V

■ Outline Dimensions

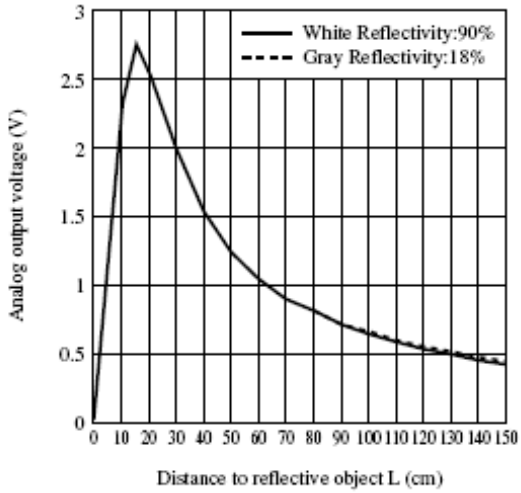
(Unit : mm)



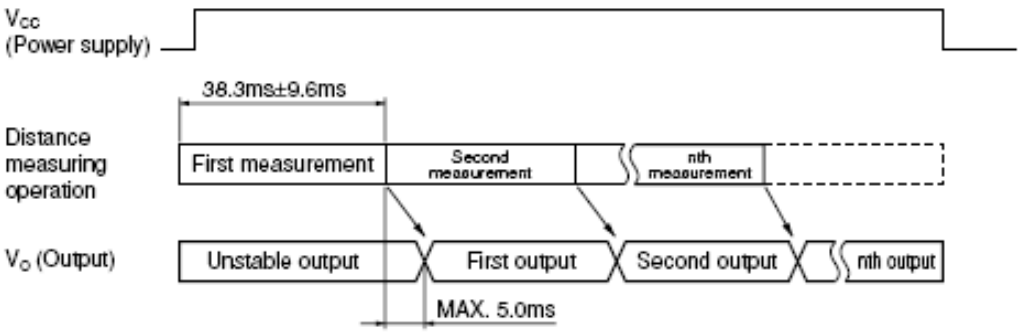
Internal Block Diagram



Analog Output Voltage vs. Distance to Reflective Object



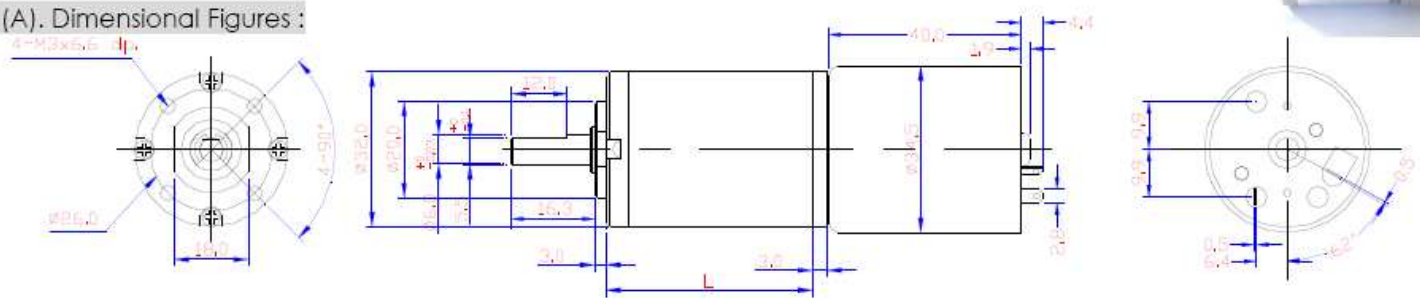
Timing Chart



Annexe 6 (Motor 12V 1/51)

Model : PK32F Series of DC Planetary Gear Motor

(A). Dimensional Figures :



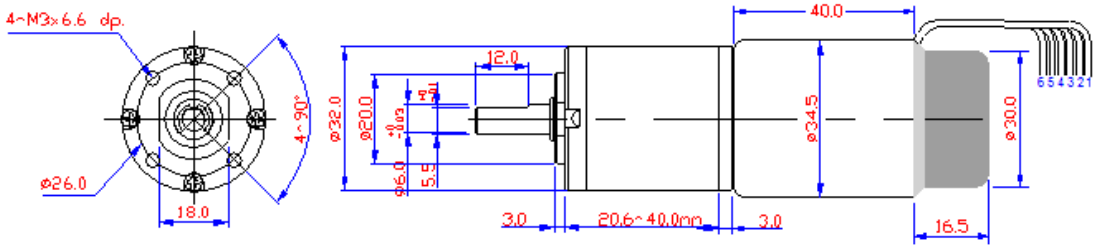
(B). Standard DC Motor Specifications :

DESCRIPTION	Rated Voltage	Speed	Current	Torque	Output	Eff
	VDC	RPM	mA	g-cm	W	%
NO LOAD	12V	6000 ± 600	approx. 136			
	24V	6000 ± 600	approx. 50			
AT MAX. EFF	12V	5000	approx. 710	approx. 105	approx. 5.4	63
	24V	5100	approx. 320	approx. 105	approx. 5.4	71
AT STALL	12V		approx. 3755	approx. 656		
	24V		approx. 2122	approx. 780		

(C). Gearbox Specifications :

Reduction Ratio	Rated Tolerance Torque	Max. Momentary Tolerance Torque	Efficiency	Radial Play of Shaft	Thrust Play of Shaft	L
1/5	2kgf-cm Max	6 kgf-cm	80%	≤ 0.05 mm	≤ 0.03 mm	17.6
1/27	6kgf-cm Max	18 kgf-cm	70%	↑	↑	24.0
1/51,1/71	12kgf-cm Max	36 kgf-cm	60%	↑	↑	30.4
1/100	12kgf-cm Max	36 kgf-cm	60%	↑	↑	30.4
1/264	12kgf-cm Max	36 kgf-cm	50%	↑	↑	36.8
1/516	12kgf-cm Max	36 kgf-cm	50%	↑	↑	36.8
1/721	12kgf-cm Max	36 kgf-cm	50%	↑	↑	36.8

Model: EM3516 One / Two Channel Hall Effect Encoder



■ **Resolution :** **12 Resolution P/R**

■ **Electrical Specifications**

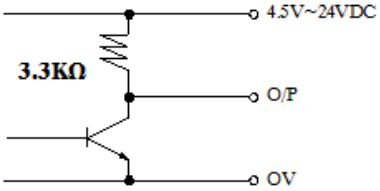
Power Source	4.5 ~ 24VDC
Current Consumption	30mA or below
Response Frequency	20KHz
Output Mode	With pull up resistor
Output Signal	A, A&B

※ Please indicate which is the resolution P/R and rotational direction when placing an order.

■ **Feature**

- Hall Effect Sensor
- Speed Position Detection
- Low cost

■ **Output Circuit :**



■ **One Channel Encoder Connections :**

1. Black : HALL SENSOR GND
2. Red : HALL SENSOR Vcc
3. White : HALL SENSOR Aout
4. Green : EMPTY
5. Brown : +MOTOR
6. Blue : -MOTOR

■ **Two Channel Encoder Connections :**

1. Black : HALL SENSOR GND
2. Red : HALL SENSOR Vcc
3. White : HALL SENSOR A Vout
4. Green : HALL SENSOR B Vout
5. Brown : +MOTOR
6. Blue : -MOTOR

Annexe 7 (Option)

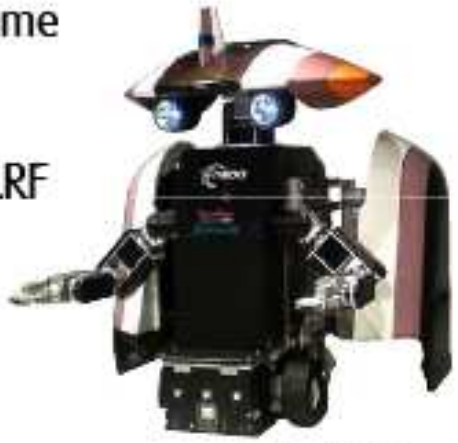
Robotics

URG-04LX-UG01

Low Cost Compact LRF from HOKUYO

Laser Range Finders (LRF) provide continuous time stamped mapping information.

The URG-04LX-UG01 is the smallest & lightest LRF available. With a single USB connection it is ideally suited to mobile robotic applications



Detection performance in the indoor environment with the existence of two pedestrians

- 5.6 metres range
- 240° scan 0.35° resolution
- 10 scans per second
- Compact: 50 x 50 x 70mm
- Lightweight 160g
- Low Power 5V DC, 2.5W

Annexe 7 (Option)

UTM-30LX

FDA approved
SOKUIKI sensor for intelligent robots

30m and 270° scanning range. Suitable for robots with higher moving speed because of the longer range and fast response.

Model No.	UTM-30LX
Power source	12VDC ± 10%(Current consumption:Max:1A,Normal:0.7A)
Light source	Semiconductor laser diode(λ =905nm) Laser safety Class 1(FDA)
Detection Range	0.1 to 30m(White Square Kent Sheet 500mm or more),Max.60m 270°
Accuracy	0.1 to 10m:±30mm, 10 to 30m:±50mm[*1]
Angular Resolution	0.25° (360° /1,440 steps)
Scan Time	25msec/scan
Sound level	Less than 25dB
Interface	USB2.0(Full Speed)
Synchronous output	NPN open collector
Command system	Exclusively designed command SCIP Ver.2.0
Connection	Power and Synchronous output:2m flying lead wire USB:2m cable with type-A connector
Amblent(Temperature/Humidity)	-10 to +50 degrees C, less than 85%RH(without dew and frost)
Vibration Resistance	Double amplitude 1.5mm 10 to 55Hz, 2 hours each in X, Y and Z direction
Impact Resistance	196m/s^2, 10 times in X, Y and Z direction
Weight	Approx. 370g(with cable attachment)

Annexe 7 (Option)

Robotics

UTM-30LX-EW

Long Range HOKUYO LRF

Model	UTM-30LX-EW
Power Source	12V DC +/- 10% , Current usage Max 1A at start-up, Normal use 0.7A
Light Source	Pulsed laser diode (λ=905nm), Laser safety class 1
Principle	Direct Time of Flight
Detection Range	0.1m to 30m (500mm x 500mm or more, White Kent Sheet)
Multi-Echo function	Max 3 output of distance per step
Accuracy	0.1m to 10m +/- 30mm, 10m to 30m +/- 50mm
Scan Window & Resolution	270° Resolution 0.25°
Scan speed	25ms/scan
Communication protocol	SCIP2.2 (Exclusive command)
Interface	Ethernet 100 Base-TX (Auto-negotiation) TCP/IP Synchronous output: NPN open collector
Connection	Power / synchronous output cable 2m Ethernet RJ-45 with male connector 30cm (female connector included)
Physical dimensions	62 x 62 x 87mm Weight 370g
Operating temperature / humidity	-10 to +50°C @ 85% humidity (no condensing or icing) (Storage -25 to +75°C)
Vibration resistance	Double amplitude 1.5mm, 10 to 55Hz each for 2 hours in X,Y,Z Directions
Impact Resistance	196m/s² each 10 times in in X,Y,Z Directions

- 30 metres range
- Designed for outdoor use
- 270º scan 0.25º resolution
- 40 scans per second
- Compact: 62 x 62 x 87mm
- Lightweight: 400g
- Power frugal: 12VDC, 8.4W
- Ethernet connectivity
- Multi-Echo functionality
- Effective in adverse weather

SENTEK solutions

Annexe 8 (Option)

Optional Sensor: Kinect
(+DC/DC+fixation sur rotule avec niveau à bulle)

Annexe 9 (Option)

(OpenWRT Mesh Network possible)

UBIQUITI NETWORKS

TECHNICAL SPECS / DATASHEET

PicoStation M2-HP 2.4GHz Hi Power 802.11N Outdoor Radio System

World's Smallest and Most Powerful Outdoor WiFi AP

SYSTEM INFORMATION	
Processor Specs	Atheros MIPS 24KC, 400MHz
Memory Information	32MB SDRAM, 8MB Flash
Networking Interface	1 X 10/100 BASE-TX (Cat. 5, RJ-45) Ethernet Interface

REGULATORY / COMPLIANCE INFORMATION	
Wireless Approvals	FCC Part 15.247, IC RS210, CE
RoHS Compliance	YES

OPERATING FREQUENCY 2412MHz-2462MHz

TX POWER SPECIFICATIONS			
	DataRate	Avg. TX	Tolerance
11g	1-24Mbps	28 dBm	+/-2dB
	36Mbps	27 dBm	+/-2dB
	48Mbps	26 dBm	+/-2dB
	54Mbps	24 dBm	+/-2dB
Airmax 11n	MCS0	28 dBm	+/-2dB
	MCS1	28 dBm	+/-2dB
	MCS2	28 dBm	+/-2dB
	MCS3	28 dBm	+/-2dB
	MCS4	27 dBm	+/-2dB
	MCS5	25 dBm	+/-2dB
	MCS6	24 dBm	+/-2dB
	MCS7	23 dBm	+/-2dB

RX SPECIFICATIONS			
	DataRate	Sensitivity	Tolerance
11g	1-24Mbps	-97 dBm min.	+/-2dB
	36Mbps	-80 dBm	+/-2dB
	48Mbps	-77 dBm	+/-2dB
	54Mbps	-75 dBm	+/-2dB
Airmax11n	MCS0	-96 dBm	+/-2dB
	MCS1	-95 dBm	+/-2dB
	MCS2	-92 dBm	+/-2dB
	MCS3	-90 dBm	+/-2dB
	MCS4	-86 dBm	+/-2dB
	MCS5	-83 dBm	+/-2dB
	MCS6	-77 dBm	+/-2dB
	MCS7	-74 dBm	+/-2dB

ANTENNA & RANGE PERFORMANCE	
RP-SMA Antenna Included	Outdoor Omni-directional. 6dBi
Indoor/Outdoor Range	Over 200m / 500m

PHYSICAL / ELECTRICAL / ENVIRONMENTAL	
Enclosure Size	13.6 cm. length x 2.0 cm. height x 3.9cm. width
Weight	0.10kg
Enclosure Characteristics	Outdoor UV Stabalized Plastic
Max Power Consumption	8 Watts
Power Rating	Up to 24V. POE Supply included
Power Method	Passive Power over Ethernet (pairs 4,5+; 7,8 return)
Operating Temperature	-20C to +70C
Operating Humidity	5 to 95% Condensing
Shock and Vibration	ETSI300-019-1.4

Annexe 10 (Option)

Mini-PCI

MP-323 - Mini-PCI IEEE 1394a Module

Form Factor: Mini-PCI type III B with 124-pin interface.
Controller: Agere FW323.
Output Function: 3 x 8-pin IEEE1394a Connector.
Dimensions: 45mm x 60mm (W x L).
Accessories: 1x 8-pin IEEE 1394a Cable.
Power Requirements: small 4-pin AT power connector for 12V.

MP-840

H.264 Hardware Compression Card with 4 Ports of Video & Audio Inputs

Features
- Mini-PCI interface
- H.264 Hardware Compression
- 4-ch Video & Audio inputs
- Support D1
- Windows XP, Vista (32-bit) SDK & Driver

MP-878D2

2-ch Mini-PCI capture card with Software Develop Kit

Features
- Mini-PCI interface
- 2-ch Video input
- Support D1 , CIF resolution
- Windows Driver & SDK provide
- Linux Driver provide

MP-6100

H.264 Hardware Compression Card with 4 Ports of Video & Audio Inputs

Features
- Mini-PCI interface
- H.264 Hardware Compression
- 4-ch Video & Audio inputs
- Support D1 , CIF
- Windows / Linux SDK & Driver

Annexe 11 (Option)

Optional CPU (core I5 520M or core I7 620M)

Industrial Single Board Computer

3.5'' Miniboard

LS-377

Support Intel® Core™ i7, Core™ i5 and Core™ i3 CPU with DDRIII SO-DIMM, CRT, LVDS, DVI, Gigabit LAN, Mini PCI, PCI Express mini card, Serial ATAII, 7.1Channel HD Audio

Form Factor	3.5'' Miniboard
CPU	Intel® Core™ i7, Core™ i5, Core™ i3, Celeron®, and Pentium® Mobile Processor Package type: rPGA988A
Memory	1 x DDRIII SO-DIMM 800/1066 MHz up to 4GB
Chipset	Intel QM57
Real Time Clock	Chipset integrated RTC with onboard lithium battery
Watchdog Timer	Generates a system reset with internal timer for 1min/s ~ 255min/s
Power Management	Supports ACPI 2.0 compliant.
Serial ATA Interface	2 x serial ATAII interface with 300MB/s transfer rate
VGA Interface	Onboard VGA (depend on CPU)
LVDS Interface	Onboard 24-bit dual channel LVDS connector with +3.3V/+5V/+12V supply
DVI Interface	DVI interface
Audio Interface	Realtek ALC888 HD Audio
LAN Interface	1 x Intel 82574L Gigabit LAN
GPIO Interface	Onboard programmable 8-bit Digital I/O interface
Extended Interface	1 x Mini PCIE socket, 1 x Mini PCI socket to support Mini PCI Type IIIA
Internal I/O Port	1 x RS232/422/485, 1 x SMBUS, 1 x GPIO, 4 x USB ports, 1 x IrDA, 1 x LVDS, 1 x DVI, 1 x LCD, 2 x Serial ATA, 1 x LCD Inverter, 1 x HD Audio, 1 x DIO, 1 x DCOUT and 1 x CDIN
External I/O Port	1 x PS/2, 1 x LAN ports, 1 x VGA port, 2 x USB2.0 ports, 1 x RS232 port
Power Requirement	9~24V full range DC Input
Dimension	146mm x 101mm
Temperature	Operating within 0~60 centigrade Storage within -20~85 centigrade

Annexe 12 GPS (Option)

Module GPS "XBU-353" à sortie USB

Le "XBU-353" est un récepteur GPS ultra compact à sortie USB livré dans un petit boîtier magnétique étanche très esthétique. Livré avec un CD-ROM comprenant des drivers ainsi qu'un logiciel de test, ce modèle 20 canaux est basé sur un chipset SiRF StarIII™ qui lui confère une sensibilité exeptionnelle de l'ordre de -159 dBm.

Capable de supporter la démodulation WASS™, le "XBU-353" dispose d'un câble d'une longeur de 1,50 m et d'une Led de contrôle allumée lors de la recherche de position et clignotante lorsque la position a été trouvée. Une "super capacité" de sauvegarde est également intégrée au module.

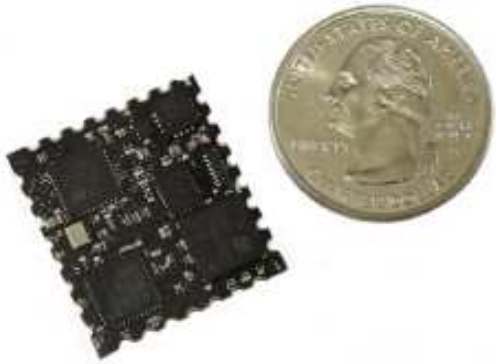
Dimensions	Diamètre: 53 mm x 19.2 mm
Alimentation	+4.5 à +6.5 Vcc
Consommation	80 mA
Canaux	20
Position	10 m, 2D RMS
Vélocité	515 m/sec.
Altitude maxi.	18.000 mètres
Accélération	< 4 g
Temps de réacquisition	0.1 sec.
Hot Start	1 sec.
Warm Start	38 sec.
Cold Start	42 sec.
Signal de sortie	SiRF binary : Position, Velocity, Altitude, Status et Control NMEA 0183 : GGA, GSA, GSV, RMC

Annexe 13 IMU (GPS)

VECTORNAV
Embedded Navigation Solutions

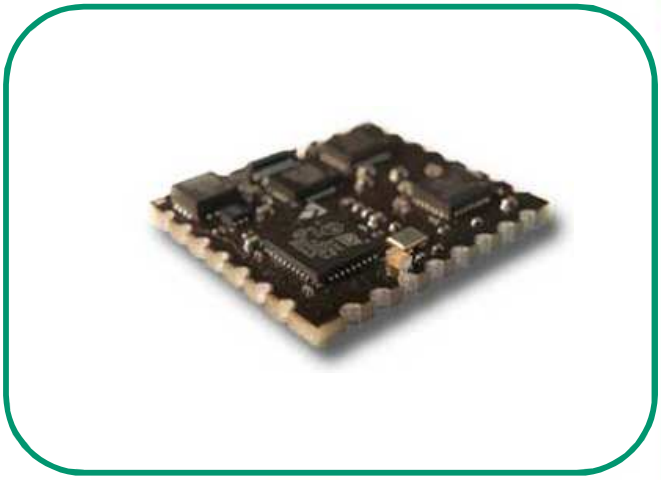
VN-100

Embedded Attitude Heading Reference System



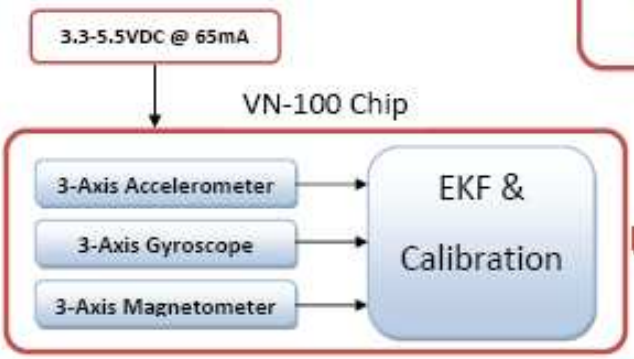
The VN-100 is the world's first Attitude Heading Reference System (AHRS) integrated into a single chip sized module. It's small size and high performance opens the door for numerous embedded applications.

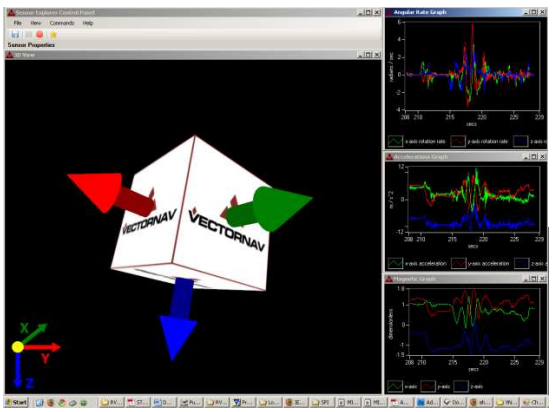
Watch our video demonstration at:
http://tinyurl.com/vectornav



Features

- Single surface mount solution
- Small SMT footprint < $1in^2$
- Accuracy < 0.5 deg rms (static)
- Fully calibrated at room temp
- Extended Kalman Filter (EKF) attitude solution at 200 Hz
- Serial TTL, SPI Outputs
- Euler angles, quaternion, DCM, acceleration, angular rates, magnetic outputs
- Low cost





Performance

Heading	
Range	±180 °
Accuracy (rms)	< 2.0 °
Resolution	< 0.2 °

Attitude	
Range: Pitch, Roll	±180 °, ±90 °
Accuracy	< 0.5 °
Resolution	< 0.06 °

Angular Rate	
Range: Heading	±300 °/sec
Range: Pitch, Roll	±500 °/sec
Bias Stability: Heading	< 0.1 °/sec @ 25°C
Bias Stability: Pitch, Roll	< 0.06 °/sec @ 25°C
Resolution: Heading	< 0.2 °/sec
Resolution: Pitch, Roll	< 0.06 °/sec
Bandwidth: Heading	80 Hz
Bandwidth: Pitch, Roll	140 Hz

Acceleration	
Input Range: X/Y/Z	±2 g, ±6 g
Bias Stability: X/Y	< 0.5 mg @ 25°C
Bias Stability: X/Y	< 1.6 mg @ 25°C
Resolution: X/Y	< 0.4 mg
Resolution: Z	< 2 mg
Bandwidth	50 Hz

Annexe 14 (Option)

AC/DC Multi-Functional Balance Silent Charger/Discharger
(On doit éteindre le robot)
Chargeur rapide AC/DC Multifonctions charge/décharge équilibreur silencieux Avec monitoring USB par PC