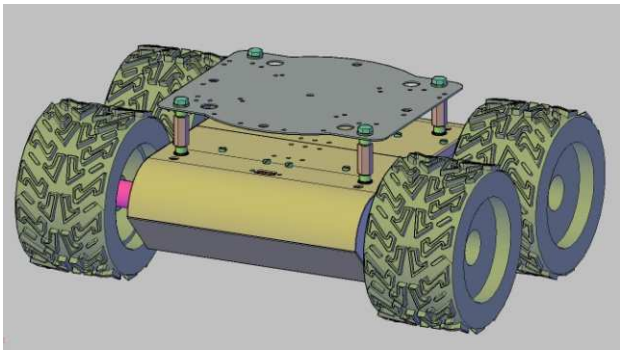


- ***4 roues motrices***
  (2 roues + 1 roue folle possible)
- ***Architecture modulaire et ouverte***
- ***Contrôlable en RS232 ou en Wifi***
- ***PC x86 embarqué avec une image XPe(ou Linux Xubuntu)***

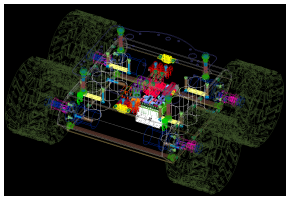
Wifibot ***Lab***

Robot WIFIBOT Lab

Le Wifibot Lab est une plate forme robotique **modulaire**, qui permet de couvrir un large spectre lié à la **robotique mobile**, à **l'informatique industrielle** et **aux réseaux sans fil**. Utilisée par un nombre croissant de centre R&D, d'école, d'université, et de laboratoire dans le monde, elle se distingue par sa simplicité et son efficacité.
Le système de base est composé d'un **châssis en aluminium** anodisé, d'une **camera USB motorisée**, de **2 capteurs infra rouge** et d'une nappe laser **Hokuyo URG-04LX-UG01 en option**. Le châssis du robot est contrôlable en utilisant un port RS232. L'unité de calcule qui envoie les commandes au robot est une carte industrielle Intel Atom D510 double coeur au format 3.5 pouces, avec une image du système d'exploitation XP embedded SP3 (ou Linux Ubuntu) utilisés dans le monde de l'embarqué. Une carte WIFI assure la liaison sans fils au système avec le point **d'accès fourni**.
Les utilisateurs peuvent ainsi modifier ou concevoir des programmes directement sur le robot (VGA/DVI ou bureau distant via WIFI).
Diverses interfaces de contrôle et API sont proposées aux utilisateurs avec le code source en C/C++. Des logiciels avec leurs modules WIFIBOT comme **RTMAPS, URBI, Matlab** ou d'autres peuvent s'interfacer facilement du fait de la simplicité du protocole RS232 ou Ethernet.
La carte bas niveau moteur est aussi programmable en C avec le débuggeur ICD2/3 et l'outil MPLAB de Microchip, ou simplement, en utilsant le bootloader intégré.
Divers options peuvent être ajouté au cour du temps: Carte d'acquisition multi camera H264, carte firewire, Camera avec DSP Texas Davincy setc...

Option

www.wifibot.com

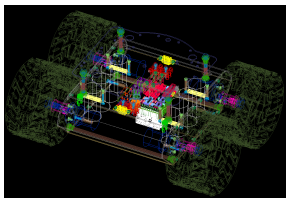


Windows Embedded

Wifibot Lab

Spécifications par défaut

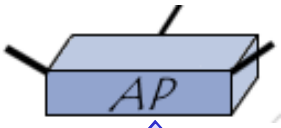
Capteurs moteur:	2 codeurs en quadrature effet hall 2048 tics par tour de roue.
Control vitesse :	2 x PID sur 1 x DSPIC Microchip 33f programmés en C Débuggeur ICD2/3 (option)
Moteurs:	4x moteurs 12V Réduction 52:1 planétaire 156 rpm
Dimensions:	L : 30 cm W : 35 cm H : 15 cm W : 3.5Kg
Batteries:	12V NiMh (LIFE 12V possible) 9000 mAH Chargeur 12V/220V Path Power Managment sur 2 Jack : Charge + Alim DC 14-15v .
Bus de contrôle interne:	RS232. Le protocole est très simple et permet de contrôler le robot via l'API en C/C++ ou par n'importe qu'elle logiciel du commerce comme MatLab, RTMAPS, Robotics Studio, URBI …
Protocole de contrôle distant :	Socket TCP/UDP via WIFI ou RJ45
Calculateur:	Carte industrielle Intel Atom D510 double coeur 1.6Ghz 1G Ram / 4G CF 4 x USB 2.0 4 x RS232/485 1 x Mini-Pci + 1x mini pcie …
Capteurs:	2 capteurs infra rouge 1 web cam Pan et Tilt 1 Lidar Hokuyo 4m **en option**
Logiciels:	API C++ de contrôle du robot 2 interfaces de contrôle distantes Serveur web embarqué



Architecture haut niveau

WifibOT *Lab*

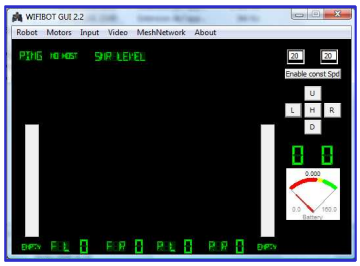
WIFI



Ethernet

Mini-PCI

Calculateur



Interface de contrôle distante

USB

USB

RS232

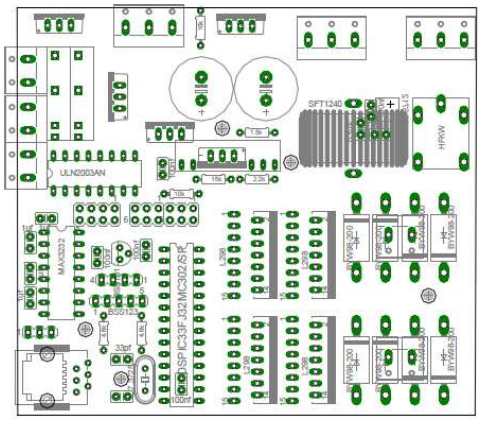
Serveur Web MJPEG

ICD2-3 (option)

Camera

Option

Lidar 4m



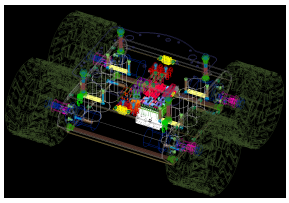
Carte Moteur DSPIC 33F

Analogue

PWM

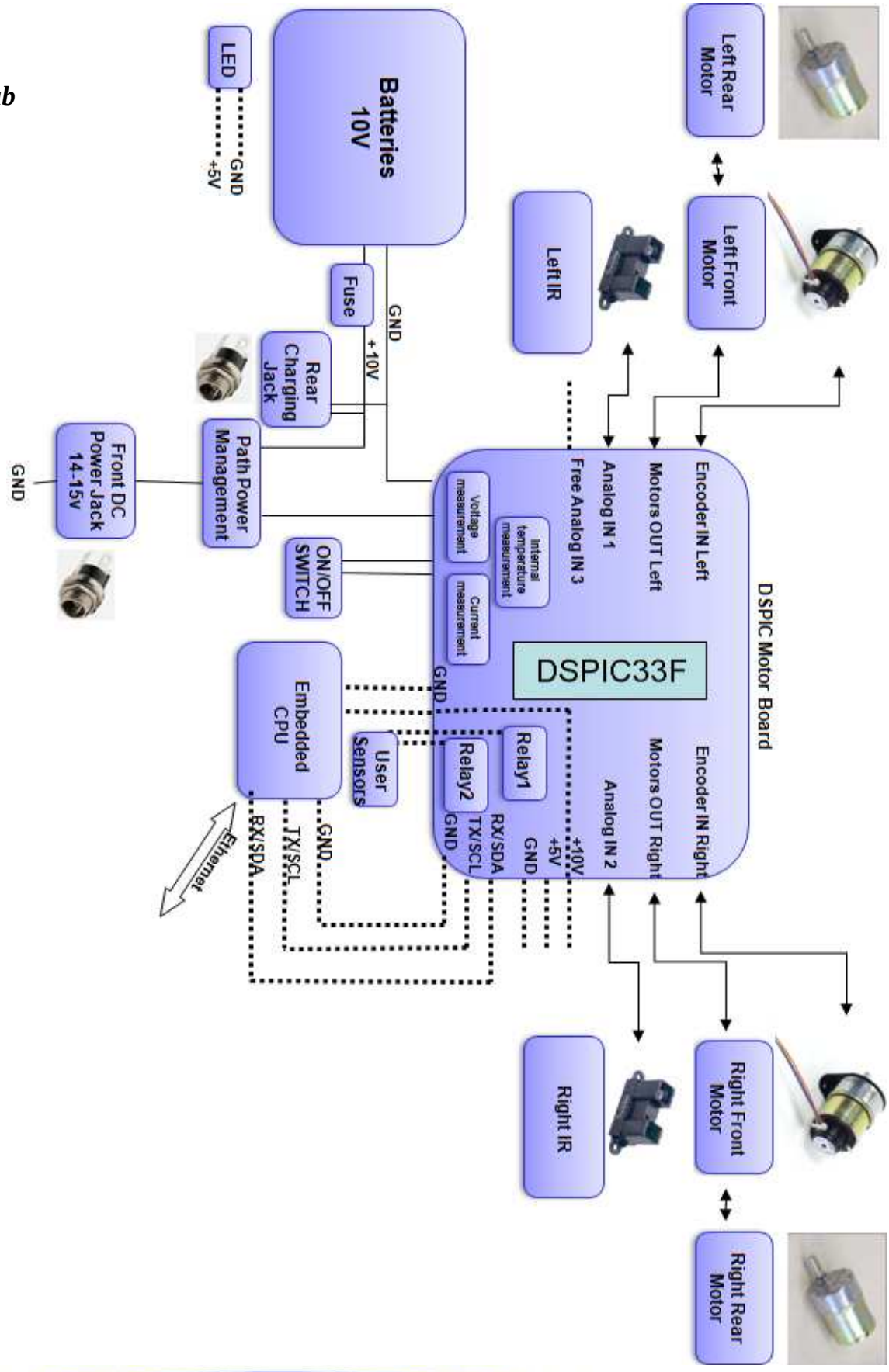
Capteurs IR x2

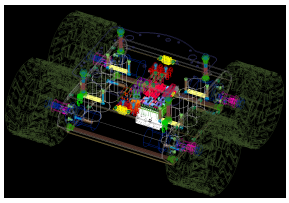
Moteur + Codeur Hall



WifiBOT *Lab*

Architecture bas niveau





Annexe 1

Wi-fibOT *Lab*

LE-376

3.5" embedded board with Intel® Atom™ dual-core Solution

LE-376 consists of the 13W Intel ATOM D510 and ICH8M, Graphic Processing Unit features power-efficient 32-bit 3D graphics core based on Intel GMA 3150 architecture, video capability with up to 384MB of shared graphics memory, delivers sophisticated graphics for large display applications and with Dual display types such as VGA+LVDS, Enables smoother playback for MPEG-2 codec, a standard video compression format used on Blu-ray, DVDs, broadcasting, and broadband content.

Specification

Form Factor	3.5" embedded board
CPU	Intel® Atom™ D510, 1.66GHz, 1MB cache (LE-376A) Package type : Micro-FCBGA (FCBGA559)
Memory	1 x 200-pin DDR2-667 SO-DIMM up to 4GB (LE-376H/A) Support Non-ECC, unbuffered memory only
Chipset	Intel® ICH8M
Real Time Clock	Chipset integrated RTC with onboard lithium battery
Watchdog Timer	Generates a system reset internal timer for 1min/sec ~ 255min/sec
Power Management	ACPI 2.0 compliant, supports power saving mode
Integrated Graphics	Intel® integrated extreme GMA 3150 Technology
Video Memory	Up to 384MB shared with system memory
LVDS Interface	Chipset Integrated 18-bit single channel LVDS
Serial ATA Interface	2 x SATAII interface with 300MB/s transfer rate
Solid State Disk	1 x Compact Flash Type-II
Audio Interface	Intel® ICH8M integrated with Realtek ALC888 HD Codec
LAN Interface	3 x Intel® 82583V Gigabit Ethernet controller
Expansion Interface	1 x PCIe mini card & 1 x Mini-PCI socket
Internal I/O Port	1 x Audio, 4 x USB2.0, 1 x LVDS, 1 x LCD Inverter, 1 x LPT 1 x RS232/4224/5, 4 x RS232, 1 x SMBUS, 1 x IrDA
External I/O Port	1 x USB, 3 x RJ45 LAN, 1 x DB15 VGA, 1 x RS232
Power Requirement	DC 9V ~ 24V input

Annexe 2

WLAN 802.11a/b/g mini-PCI Module

DCMA-81

SPECIFICATION

Frequency Band	➢ 2.312 – 2.472GHz, 2.484 GHz ➢ U-NII: 5.15 - 5.35GHz, 5.725 - 5.825GHz ➢ ISM: 5.725 – 5.850 GHz ➢ DSRC: 5.850 – 5.925 GHz ➢ Europe: 5.15 - 5.35GHz, 5.47 - 5.725GhHz ➢ Japan: 4.90 – 5.00GHz, 5.03 – 5.091GHz, 5.15 – 5.35GHz
Modulation technique	➢ **802.11 a/b/g** DSSS (DBPSK, DQPSK, CCK) OFDM (BPSK,QPSK, 16-QAM, 64-QAM)
Host interface	Half size Mini PCI Type 3A
Channels support	➢ **802.11b/g** US/Canada: 11 (1 ~ 11) Major European country: 13 (1 ~ 13) France: 4 (10 ~ 13) Japan: 11b: 14 (1~13 or 14th), 11g: 13 (1 ~ 13) ➢ **802.11a** US/Canada:12 non-overlapping channels Europe: 19 non-overlapping channel Japan: 4 non-overlapping channels
Output power	➢ A Mode: +17dBm at 6, 9, 12, 18, and 24Mbps +16dBm at 36Mbps +14dBm at 48Mbps +13dBm at 54Mbps ➢ B Mode: +19dBm at 1,2, 5.5, and 11Mbps ➢ G Mode: +17dBm at 6, 9, 12, 18, 24 and 36Mbps +16dBm at 48Mbps +15dBm at 54Mbps
Operation distance	➢ **802.11a:** Outdoor: 85m@54Mbps, 250m@6Mbps Indoor: 20m@54Mbps, 40m@6Mbps ➢ **802.11b:** Outdoor: 250m@11Mbps, 300m@1Mbps Indoor: 30m@11Mbps, 50m@1Mbps ➢ **802.11g**: Outdoor: 80m@54Mbps, 250m@6Mbps Indoor: 15m@54Mbps, 35m@6Mbps
Operation System supported	➢ Windows® 2K, XP
Dimension	➢ 59.75mm(L) * 25.50mm (W) * 5mm (H)
Security	➢ 64-bit,128-bit, 152-bit WEP Encryption ➢ 802.1x Authentication ➢ AES-CCM & TKIP Encryption
Operation mode	➢ Infrastructure & Ad-hoc mode
Operation temperature	➢ 0°C ~ 70°C
Storage temperature	➢ -20°C ~ 70°C

Annexe 3

108M Wireless Access Point
TL-WA601G

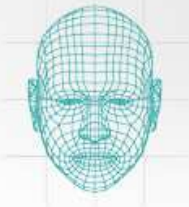
Specifications:

Standards	IEEE 802.11g, IEEE 802.11b
Interface	1 10/100M auto-sensing LAN Port
Wireless Signal Rates With Automatic Fallback	Super G™ : 108M 11g: 54/48/36/24/18/12/9/6M(dynamic) 11b: 11/5.5/2/1M(dynamic)
Frequency Range	2.4-2.4835GHz
Wireless Transmit Power	20dBm(Max)
Antenna	3dBi detachable Omni directional antenna
Modulation Technology	IEEE 802.11b: DQPSK, DBPSK, DSSS, and CCK IEEE 802.11g: BPSK, QPSK, 16QAM, 64QAM, OFDM
Receiver Sensitivity	108M: -68dBm@10% PER 54M: -68dBm@10% PER 11M: -85dBm@8% PER 6M: -88dBm@10% PER 1M: -90dBm@8% PER 256K: -105dBm@8% PER
Power Supply Unit	Input: localized to country of sale Output: 9VAC / 0.8A linear PSU
Operating temperature	0°C~40°C (32°F~104°F)
Storage temperature	-40°C~70°C (-40°F~158°F)
Relative humidity	10% ~ 90%, non condensation
Storage Humidity	5%~95% non-condensing
Dimensions	6.2×4.3×1.3 in. 158×110×32 mm

Annexe 4

Technical Specifications

- Motorized tracking (189° horizontal and 102° vertical)
- Carl Zeiss® optics
- Autofocus lens system
- Ultra-high resolution 2-megapixel sensor with RightLight™ 2 Technology
- Color depth: 24-bit true color
- Video capture: Up to 1600 by 1200 pixels (HD quality)
- Still-image capture: 8 megapixels (with software enhancement)
- Built-in microphone with RightSound™ Technology
- Frame rate: Up to 30 frames per second
- High-Speed USB 2.0
- Logitech QuickCam® software (with Video Effects™, filters, avatars, and face accessories)
- Works with Skype™, Windows Live™ Messenger, Yahoo®, AOL® and other compatible instant messaging applications



Motorized tracking

It keeps you right in the middle of the picture, offering 189-degree field of view and 102-degree tilt.

Carl Zeiss® optics

You'll enjoy razor-sharp images from a lens designed with the help of one of the pioneers in the industry. Find out more about why our collaboration with Carl Zeiss benefits you.

Learn more.

Advanced autofocus

Your images stay razor sharp, even in close-ups (up to 10 cm from the camera lens) with built-in autofocus. Learn all about Logitech autofocus.

Learn more.

HD video recording

Your friends and family can see you in widescreen video at HD quality (720p).

Higher-megapixel performance

With its true 2-megapixel sensor, with up to 8-megapixel photos (software enhanced), every video call and photo will look sharp. Megapixels? Sensor? Why is image quality so important?

Learn more.

RightLight™ 2 technology

Even if you make a video call in dim or poorly backlit settings, the camera will intelligently adjust to produce the best possible image. Find out what's right about RightLight 2 technology.

Learn more.

Annexe 5

AC/DC Multi-Functional Balance Silent Charger/Discharger

Chargeur AC/DC Multi-Fonctions charge/décharge équilibreur silencieux Avec monitoring USB par PC

GP2Y0A02YK

Long Distance Measuring Sensor

■ Features

1. Less influence on the colors of reflected objects and their reflectivity, due to optical triangle measuring method
2. Distance output type
   (Detection range:20 to 150cm)
3. An external control circuit is not necessary
   Output can be connected directly to a microcomputer

■ Applications

1. For detection of human body and various types of objects in home appliances, OA equipment, etc

■ Absolute Maximum Ratings

(T_a=25°C)

Parameter	Symbol	Rating	Unit
Supply voltage	V_{CC}	−0.3 to +7	V
*1 Output terminal voltage	V_O	−0.3 to V_{CC} +0.3	V
Operating temperature	T_{opr}	−10 to +60	°C
Storage temperature	T_{stg}	−40 to +70	°C

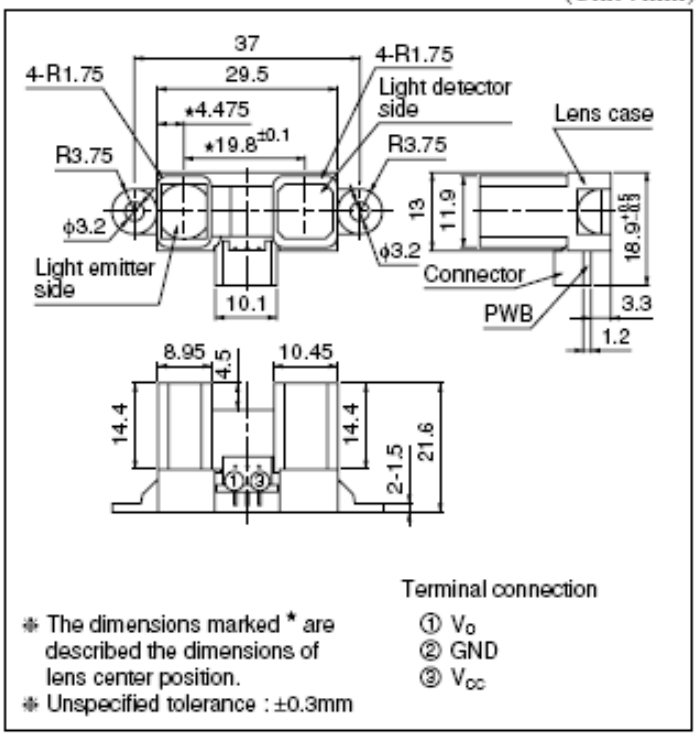
*1 Open collector output

■ Recommended Operating Conditions

Parameter	Symbol	Rating	Unit
Operating Supply voltage	V_{CC}	4.5 to 5.5	V

■ Outline Dimensions

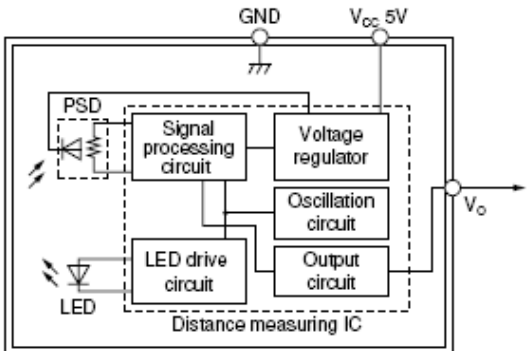
(Unit : mm)



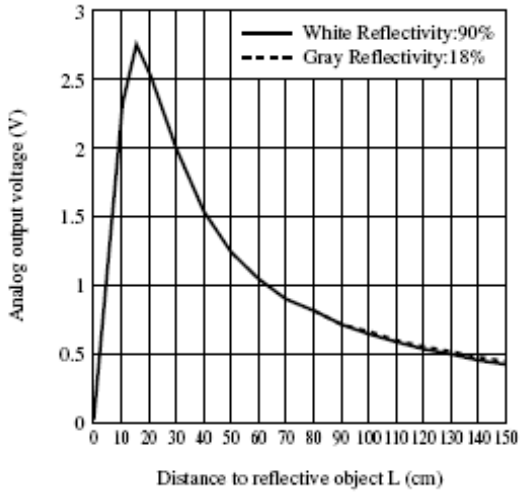
Terminal connection
① V_O
② GND
③ V_{CC}

* The dimensions marked * are described the dimensions of lens center position.
* Unspecified tolerance : ±0.3mm

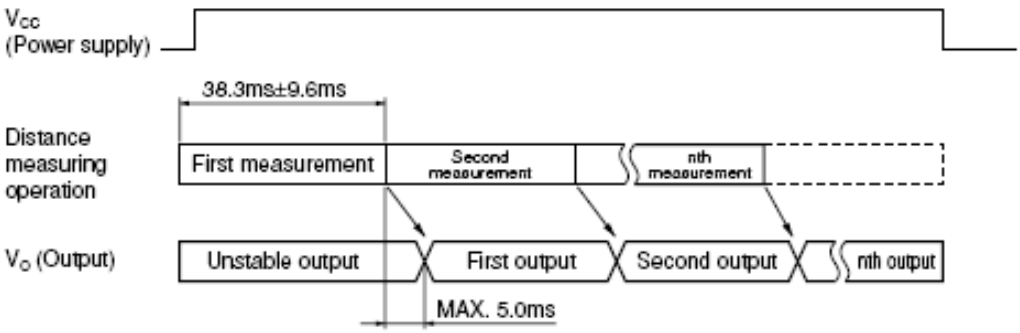
Internal Block Diagram



Analog Output Voltage vs. Distance to Reflective Object



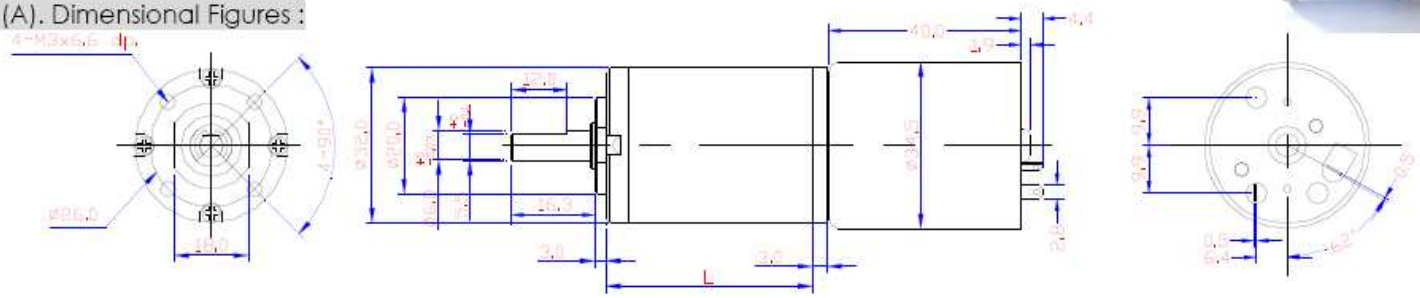
Timing Chart



Annexe 7 (Motor 12V 1/51)

Model : PK32F Series of DC Planetary Gear Motor

(A). Dimensional Figures :



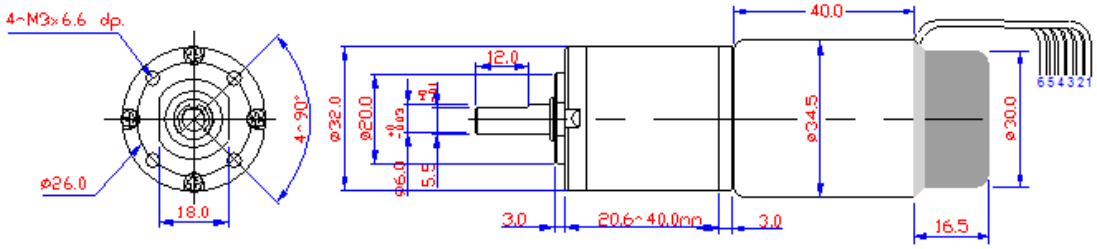
(B). Standard DC Motor Specifications :

DESCRIPTION	Rated Voltage	Speed	Current	Torque	Output	Eff
	VDC	RPM	mA	g-cm	W	%
NO LOAD	12V	6000 ± 600	approx. 136			
	24V	6000 ± 600	approx. 50			
AT MAX. EFF	12V	5000	approx. 710	approx. 105	approx. 5.4	63
	24V	5100	approx. 320	approx. 105	approx. 5.4	71
AT STALL	12V		approx. 3755	approx. 656		
	24V		approx. 2122	approx. 780		

(C). Gearbox Specifications :

Reduction Ratio	Rated Tolerance Torque	Max. Momentary Tolerance Torque	Efficiency	Radial Play of Shaft	Thrust Play of Shaft	L
1/5	2kgf-cm Max	6 kgf-cm	80%	≤ 0.05 mm	≤ 0.03 mm	17.6
1/27	6kgf-cm Max	18 kgf-cm	70%	↑	↑	24.0
1/51,1/71	12kgf-cm Max	36 kgf-cm	60%	↑	↑	30.4
1/100	12kgf-cm Max	36 kgf-cm	60%	↑	↑	30.4
1/264	12kgf-cm Max	36 kgf-cm	50%	↑	↑	36.8
1/516	12kgf-cm Max	36 kgf-cm	50%	↑	↑	36.8
1/721	12kgf-cm Max	36 kgf-cm	50%	↑	↑	36.8

Model: EM3516 One / Two Channel Hall Effect Encoder



■ **Resolution :** **12 Resolution P/R**

■ **Electrical Specifications**

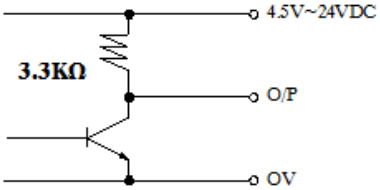
Power Source	4.5 ~ 24VDC
Current Consumption	30mA or below
Response Frequency	20KHz
Output Mode	With pull up resistor
Output Signal	A, A&B

※ Please indicate which is the resolution P/R and rotational direction when placing an order.

■ **Feature**

- Hall Effect Sensor
- Speed Position Detection
- Low cost

■ **Output Circuit :**



■ **One Channel Encoder Connections :**

1. Black : HALL SENSOR GND
2. Red : HALL SENSOR Vcc
3. White : HALL SENSOR Aout
4. Green : EMPTY
5. Brown : +MOTOR
6. Blue : -MOTOR

■ **Two Channel Encoder Connections :**

1. Black : HALL SENSOR GND
2. Red : HALL SENSOR Vcc
3. White : HALL SENSOR A Vout
4. Green : HALL SENSOR B Vout
5. Brown : +MOTOR
6. Blue : -MOTOR

Annexe 8 (OPTION)

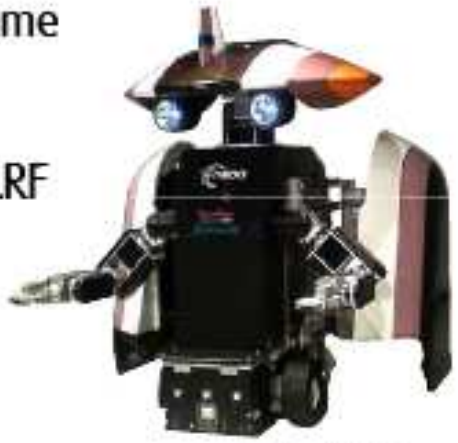
Robotics

URG-04LX-UG01

Low Cost Compact LRF from HOKUYO

Laser Range Finders (LRF) provide continuous time stamped mapping information.

The URG-04LX-UG01 is the smallest & lightest LRF available. With a single USB connection it is ideally suited to mobile robotic applications



Detection performance in the indoor environment with the existence of two pedestrians

- 5.6 metres range
- 240° scan 0.35° resolution
- 10 scans per second
- Compact: 50 x 50 x 70mm
- Lightweight 160g
- Low Power 5V DC, 2.5W

Annexe 9 (Option)

UBIQUITI NETWORKS

MiniStation

World's Smallest WiFi Platform

FREE LINUX SDK

SYSTEM INFORMATION	
Processor Specs	Atheros MIPS 4KC, 180MHz
Memory Information	16MB SDRAM, 4MB Flash
Networking Interface	1 X 10/100 BASE-TX (Cat. 5, RJ-45) Ethernet Interface

REGULATORY / COMPLIANCE INFORMATION	
Wireless Approvals	FCC Part 15.247, IC RS210
RoHS Compliance	YES

RADIO OPERATING FREQUENCY 2412-2462 MHz

TX SPECIFICATIONS			
	DataRate	TX Power	Tolerance
802.11b	1Mbps	26 dBm	+/-2dB
	2Mbps	26 dBm	+/-2dB
	5.5Mbps	26 dBm	+/-2dB
	11Mbps	26 dBm	+/-2dB
802.11g OFDM	6Mbps	26 dBm	+/-2dB
	9Mbps	26 dBm	+/-2dB
	12Mbps	26 dBm	+/-2dB
	18Mbps	26 dBm	+/-2dB
	24Mbps	26 dBm	+/-2dB
	36Mbps	24 dBm	+/-2dB
	48Mbps	22 dBm	+/-2dB
	54Mbps	21 dBm	+/-2dB

RX SPECIFICATIONS			
	DataRate	Sensitivity	Tolerance
802.11b	1Mbps	-97 dBm	+/-1dB
	2Mbps	-96 dBm	+/-1dB
	5.5Mbps	-95 dBm	+/-1dB
	11Mbps	-92 dBm	+/-1dB
802.11g OFDM	6Mbps	-94 dBm	+/-1dB
	9Mbps	-93 dBm	+/-1dB
	12Mbps	-91 dBm	+/-1dB
	18Mbps	-90 dBm	+/-1dB
	24Mbps	-86 dBm	+/-1dB
	36Mbps	-83 dBm	+/-1dB
	48Mbps	-77 dBm	+/-1dB
	54Mbps	-74 dBm	+/-1dB

ADJUSTABLE CHANNEL SIZE SUPPORT			
5MHz	10MHz	20MHz	40MHz

RANGE PERFORMANCE	
Outdoor (Antenna Dependent):	Over 50km

PHYSICAL / ELECTRICAL / ENVIRONMENTAL	
RF Connector	1xMMCX, 1x integrated PCB printed antenna
Enclosure Size	5.0.0x2.0x1.2 (cm)
Max Power Consumption	5 Watts
Power Rating	Up to 24V
Power Method	Passive Power over Ethernet (pairs 4,5+; 7,8 return)
Operating Temperature	-20C to +70C
Operating Humidity	5 to 95% Condensing
Shock and Vibration	ETSI300-019-1.4

SOFTWARE

AirOS™ by Ubiquiti Networks

Annexe 10 (Option)

Mini-PCI

MP-323 - Mini-PCI IEEE 1394a Module

Form Factor: Mini-PCI type III B with 124-pin interface.
Controller: Agere FW323.
Output Function: 3 x 8-pin IEEE1394a Connector.
Dimensions: 45mm x 60mm (W x L).
Accessories: 1x 8-pin IEEE 1394a Cable.
Power Requirements: small 4-pin AT power connector for 12V.

MP-840

H.264 Hardware Compression Card with 4 Ports of Video & Audio Inputs

Features
- Mini-PCI interface
- H.264 Hardware Compression
- 4-ch Video & Audio inputs
- Support D1
- Windows XP, Vista (32-bit) SDK & Driver

MP-878D2

2-ch Mini-PCI capture card with Software Develop Kit

Features
- Mini-PCI interface
- 2-ch Video input
- Support D1 , CIF resolution
- Windows Driver & SDK provide
- Linux Driver provide

MP-6100

H.264 Hardware Compression Card with 4 Ports of Video & Audio Inputs

Features
- Mini-PCI interface
- H.264 Hardware Compression
- 4-ch Video & Audio inputs
- Support D1 , CIF
- Windows / Linux SDK & Driver